





Product Description:

This product has a built-in three-axis integrated high-precision fiber optic gyro, high-precision quartz flexure accelerometer and a mobile mapping grade multi-mode and multi-frequency GNSS receiver that supports the autonomous BeiDou function. Through advanced intelligent combination navigation algorithm and Kalman filtering, optimized design for GNSS obstruction and multi-path interference, it can realize high-precision heading, attitude, speed and position measurement of the mobile carrier.

The inertial guidance system also has a variety of sensor interfaces, such as GNSS/odometer/DVL/barometric altimeter, etc., which can well meet the requirements of long-time, high-precision and high-reliability navigation applications in complex environments, such as urban canyons, and can be used for the navigation and control of all kinds of unmanned systems.

Features:

- Fast and accurate determination of initial heading and attitude
- Support real-time heading and attitude output
- Built-in GPS, BeiDou dual-mode receiver
- Dynamic fast alignment
- INS/GNSS combination design
- Support IE post-processing
- Anti-electromagnetic interference and vibration
- Enhanced Kalman filtering algorithm

Applications:

- Car Navigation
- Airborne Navigation
- Shipboard Navigation
- Stabilization Control

Specification:

Combined inertial/satellite navigation accuracy					
Attitude Accuracy	Direction≤0.05° (1σ) ;				
	Roll, Pitch: $\leq 0.01^{\circ}$ (1 σ)				
Position Accuracy	Point position: ≤2m (50%CEP);				
	RTK: ≤1cm+1ppm (50%CEP)				
Velocity Accuracy	$\leq 0.1 \text{m/s} (1\sigma)$				
Registration Time	me Starting from the acquisition of latitude/longitude position information, the duration of the alignment process is ≤5min.				
Inertia/ODO/DVL Accuracy	0.5% × Miles traveled (Depends on ODO or DVL accuracy)				



Specification:

Pure inertial navigation accuracy						
	Alignment accuracy: $\leq 0.2^{\circ} sec (\Phi) (1\sigma, \Phi = local latitude);$					
Attitude Accuracy	Horizontal Attitude Alignment Accuracy: ≤0.01° (1σ) ;					
	Azimuth Holding Accuracy: 0.05° (10min) (1σ);					
	Horizontal Attitude Holding Accuracy: 0.05° (10min) (1σ) .					
Position Accuracy	Position Accuracy: ≤1nmile (10min) (50%CEP)					
Velocity Accuracy	Horizontal velocity accuracy: ≤2.6m/s (10min) (1σ) 。					
Main Device Characteristic						
Gyroscopes	Range ±300°/s	Zero bias stability		≤0.05°/h (1σ)		
Accelerometers	Range ±10g	Zero bias st	ability	≤20μg (1σ)		
Physical Characteristic				Interface Characteristic		
Supply voltage	24V DC rate (12 ~ 32V DC)		Interface method	4 serial ports (RS232 or RS422)		
Electric consumption	< 30W			Support PPS, EVENTMARK input/output		
Operating temperature	-40°C~+65°C		Transmissi on speed	9600 ~ 230400bps (configure)		
Protection level	IP65 ≤136mm×136mm×130mm		77			
Physical dimension				User mode		
Weight	≤4.2Kg		Vehicle-mounted (default), aircraft-mounted, ship- mounted			

The data contained in this document is intended for the use of technical trainers only.

The customer's technical department is responsible for assessing the suitability of the product for the intended application and the completeness of the product information given in this document in relation to such application. For further information on products, technology, terms and conditions of delivery and prices, please contact our nearest office (www.senstechxyz.com).

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